

***International Symposium on Orbit Propagation and Determination,  
Lille, France , September, 26–28 2011***



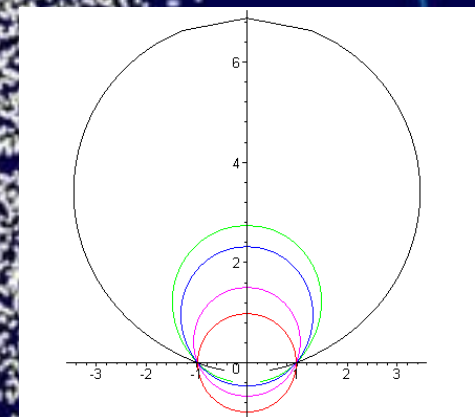
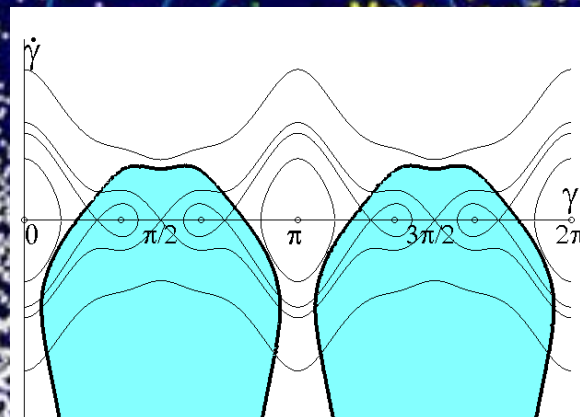
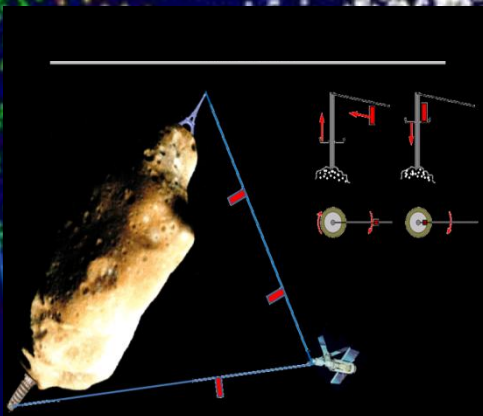
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Russia

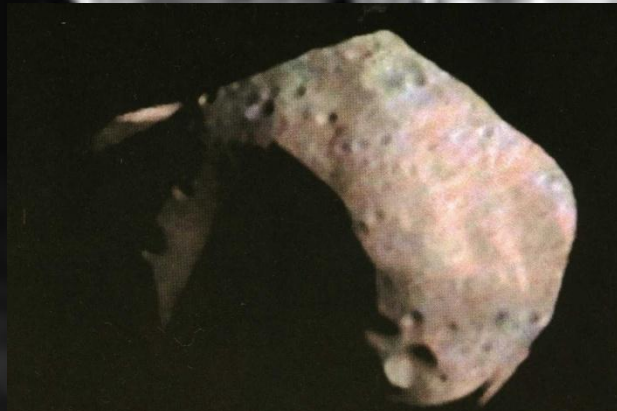
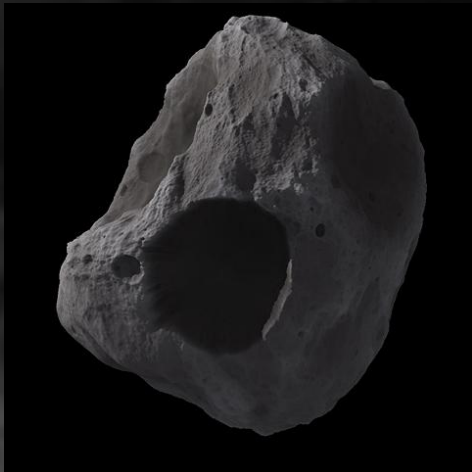
***On motions of a space station tethered to an  
asteroid (On space elevators for asteroids)***



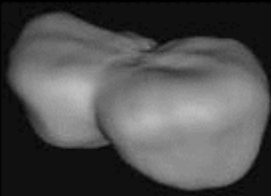
*Why should we do something excessive if we could do something better?*

## Difficulties

1. Asteroids have very complicated shapes  $\Rightarrow$
2. The asteroid rotation about mass center is not a pure rotation about one of the principal axes.  $\Rightarrow$
3. Excepting particular cases, asteroids have no stationary orbits in traditional sense
4. Influences of the Sun, the Jovi and etc. could be estimated.



## Tumbling stones

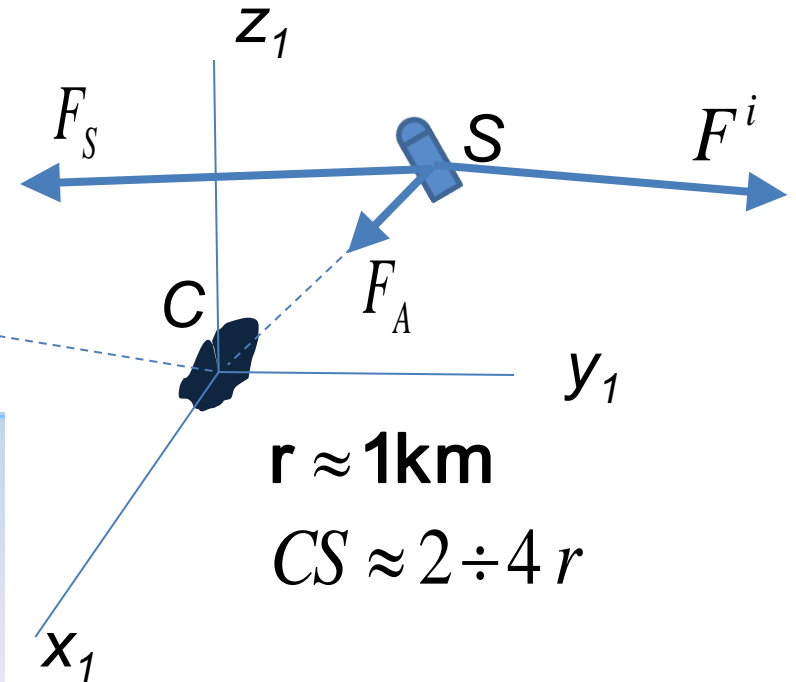


# Forces.

$Cx_1y_1z_1$  are König's axes



1-2 a.u.



C is the asteroid mass center

S is the station

$F_S$  is the Sun gravitational force

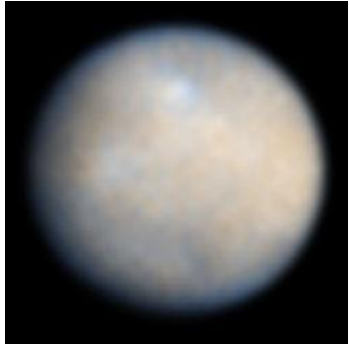
$F_A$  is the asteroid gravitational force

$F^i$  is the force of moving space

$$F_S \gg F_A, \quad \text{but} \quad \frac{|F_S - F^i|}{|F_A|} \sim 10^{-4} \div 10^{-5}$$



# Shapes.



**(1)Ceres**



**(433)Eros (?)**



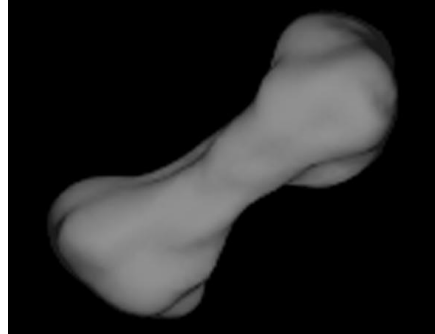
**(951)Gaspra**



**(25143)Itokawa (?)**



**(243)Ida**



**(216)Kleopatra**



**(107)Camilla**



**(4769)Castalia**



**(762)Pulcova**



**(90)Antiope**



**(4179)Toutatis (?)**



**(624)Hector**

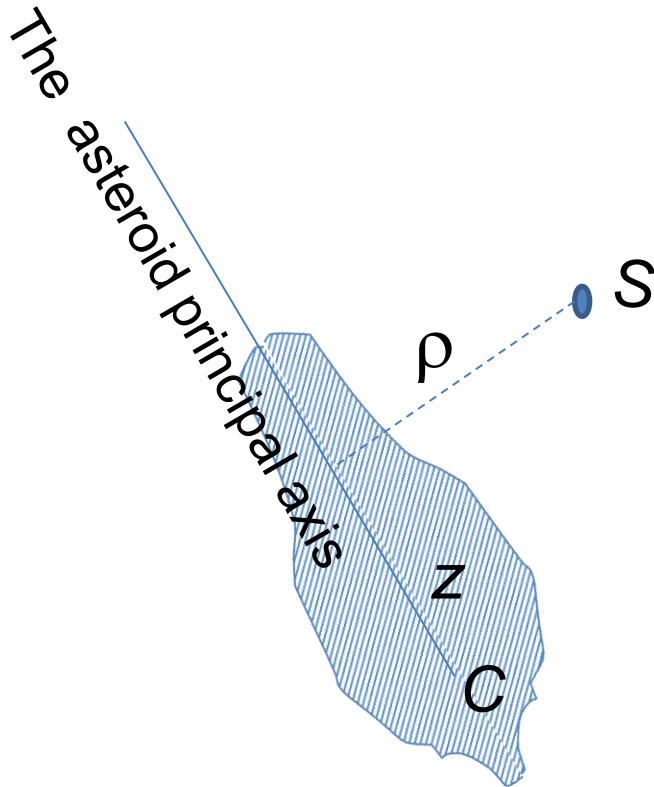


**The dumb-bell**

There is a set of dynamically symmetric or dumbbell-shaped asteroids

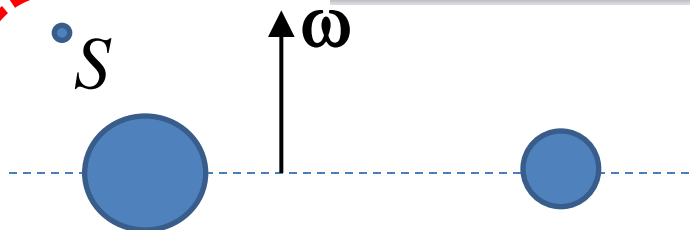
# Assumptions

1. The Sun influence on the station relative motion can be neglected
2. The asteroid is a dynamically-symmetric rigid body and its motion about the mass center is a regular precession
3. The asteroid gravitational potential depends only on  $z$  and  $\rho$ .

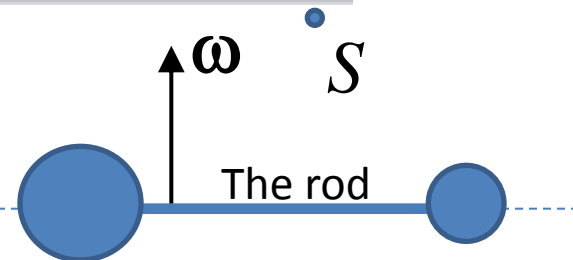
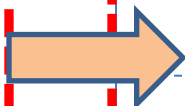


If the asteroid gravitational field is the gravitational field of two particles then the station motion describes by equations of V.V.Beletsky's problem named the **Generalized Restricted Circular Problem of Three Bodies (GRCP3B)**. In this case *Librations Points of GRCP3B* are analogies of stationary orbits.

# Comments for GRCP3B

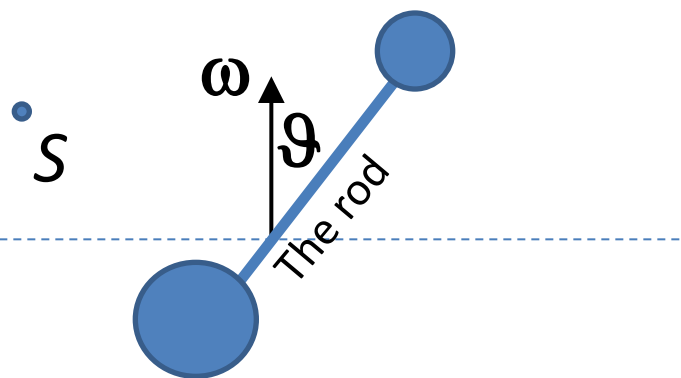
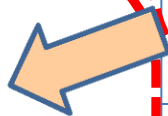


Classical RCP3B.  $\omega=1$   
5 libration points



*One-parametric generalization of RCP3B.*  $\omega>0$ , there are 5 or 3

libration points (If  $\omega$  is sufficiently big then Lagrangian points do not exist)

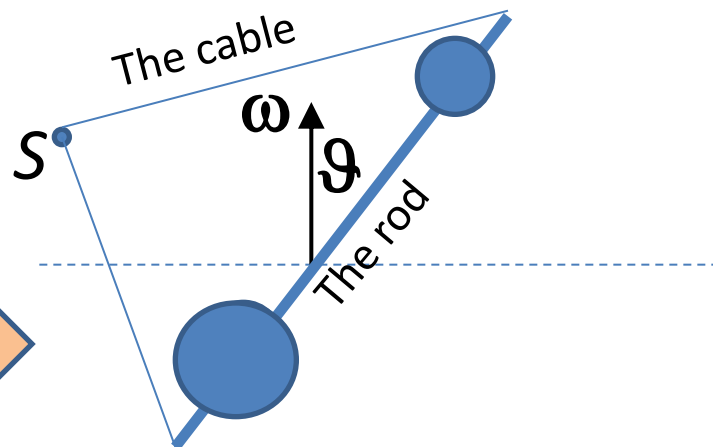
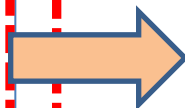


*V.V.Beletsky's two-parametric generalization of RCP3B.*

$\omega>0$   $0 \leq \vartheta \leq \pi/2$ .

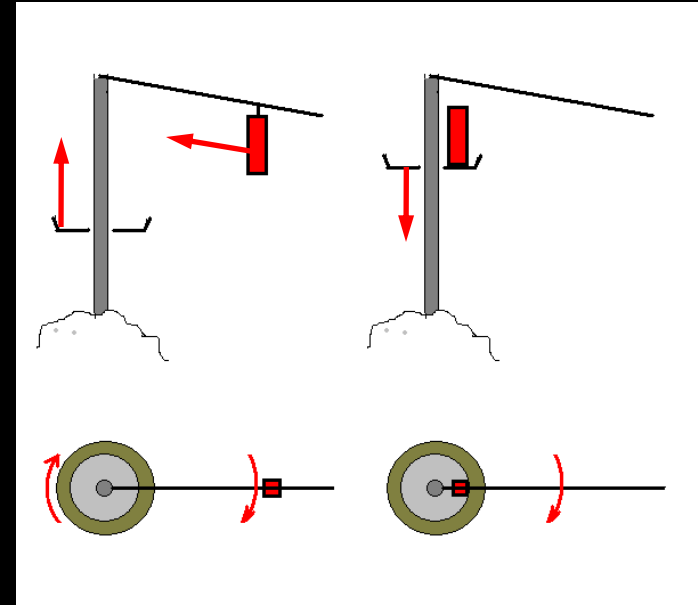
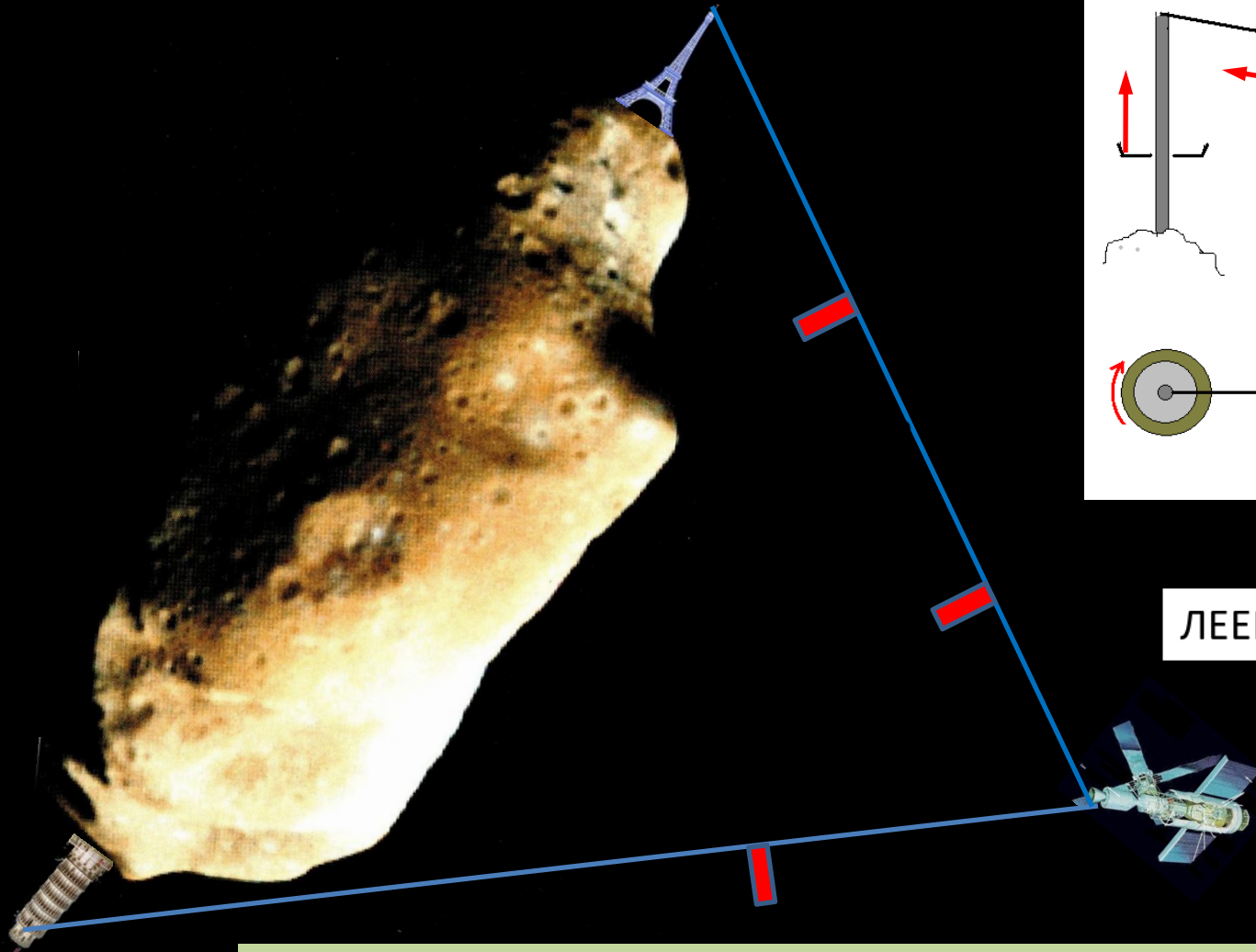
From 3 up to 9 libration points

*V.V. Beletsky //Cosmic researches, 2007, 45,3 ,  
V.V.Beletsky, A.V.Rodnikov //Cosmic  
researches, 2008, 46, 1, etc.*



The station equilibria are not only in libration points

# Space elevator based on 'the leier constraint' for an asteroid

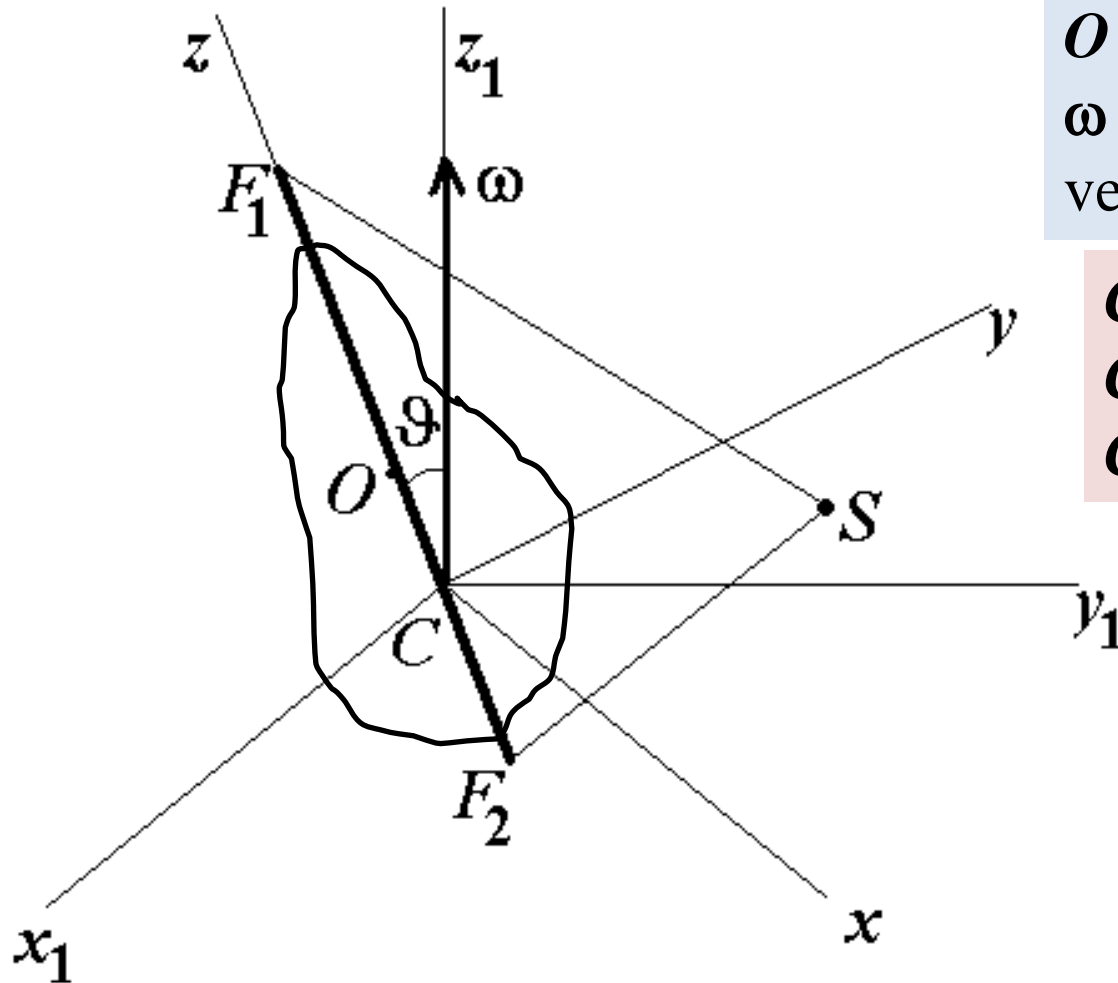


ЛЕЕРЪ

Such writing of this word is exotic even for modern Russians!

Dutch maritime term '**leier**' means the rope with both fixed ends  
(*Glossary of foreign terms in Russian, Moscow, 1959*)

# Designations, axes, parameters



$S(x,y,z)$  is the station,  
 $F_1$  and  $F_2$  are the towers,  
 $C$  is the asteroid mass center,  
 $O$  is  $F_1F_2$  midpoint,  
 $\omega$  is the precession angular velocity

$Cx_1y_1z_1$  are König's axes,  
 $Cz_1$  is the precession axis,  
 $Cx$  belong to  $Cx_1y_1$

$$e = \frac{F_1F_2}{F_1S + F_2S}$$

$$d = \frac{OC}{F_1F_2}$$

$\vartheta$  is the angle of nutation



## Dimensionless variables

The cable length  $\rightarrow 2$ ,  $\omega \rightarrow 1$ ,  
 $x \rightarrow \xi$ ,  $y \rightarrow \nu$ ,  $z \rightarrow \zeta$   
 $\rho = \sqrt{\xi^2 + \nu^2}$

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The cable length  $\rightarrow 2$ ,  $\omega \rightarrow 1$ ,  
 $x \rightarrow \xi$ ,  $y \rightarrow \nu$ ,  $z \rightarrow \zeta$   
 $\rho = \sqrt{\xi^2 + \nu^2}$

$\xi, \nu, \zeta$ or $\rho, \varphi, \zeta$ or $\varphi, \gamma$
--

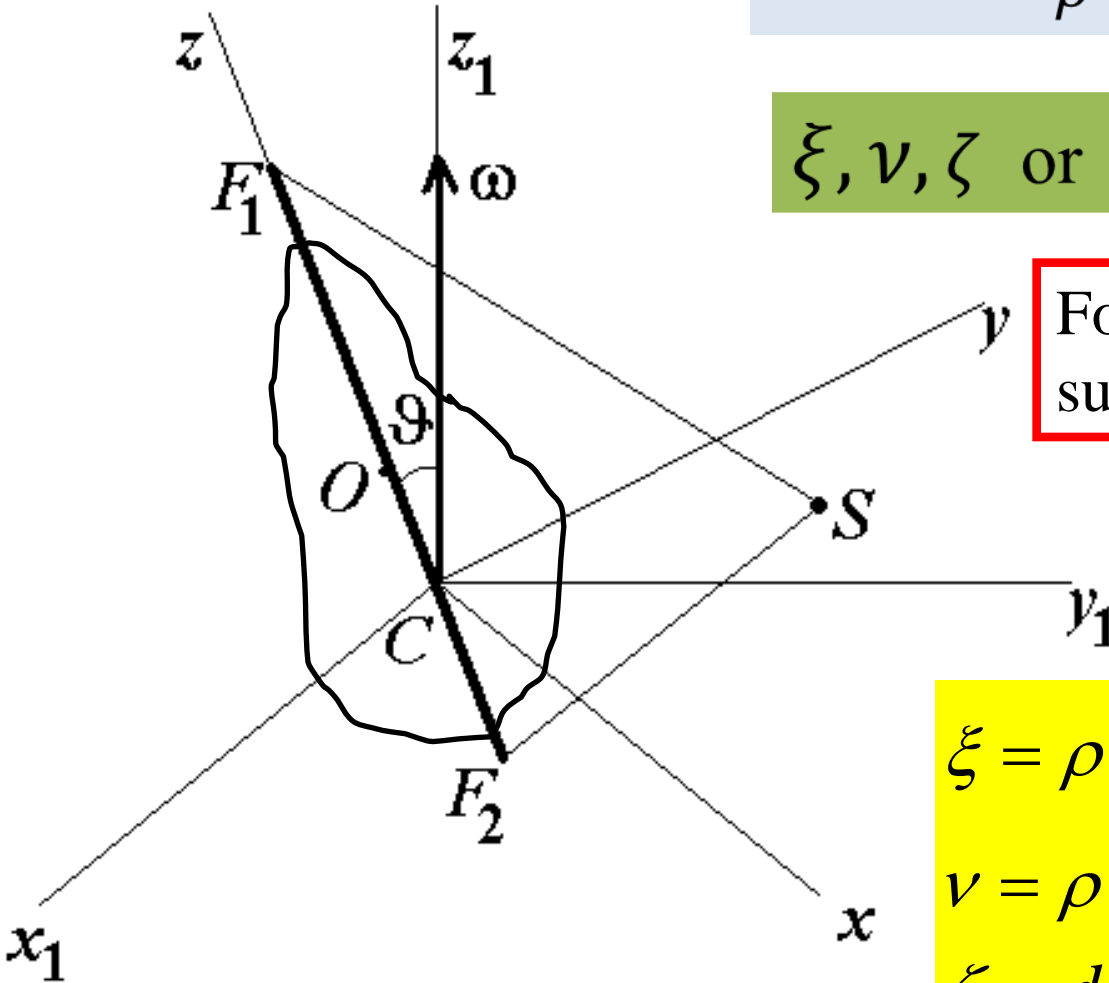
For motions on internal surface of ellipsoid

$$\frac{\rho^2}{1 - e^2} + (\zeta - ed)^2 = 1$$

$$\begin{aligned}\xi &= \rho \cos \varphi = \sqrt{1-e^2} \sin \gamma \cos \varphi \\ \nu &= \rho \sin \varphi = \sqrt{1-e^2} \sin \gamma \sin \varphi \\ \zeta &= de + \cos \gamma\end{aligned}$$

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# Motion equations

$$\rho\ddot{\varphi} + 2\dot{\rho}(\dot{\varphi} + \cos\vartheta) - 2\dot{\zeta}\sin\varphi\sin\vartheta + \cos\varphi\sin\vartheta(\rho\sin\varphi\sin\vartheta + \zeta\cos\vartheta) = 0$$

This equation does not depend on  $\tilde{\Pi}$  and  $\lambda$  !

$$\ddot{\zeta} - 2\frac{d(\rho\cos\varphi)}{d\tau}\sin\vartheta - (\zeta\sin\vartheta - \rho\cos\vartheta\sin\varphi)\sin\vartheta + \frac{\partial\tilde{\Pi}}{\partial\zeta} = \lambda\frac{\partial F}{\partial\zeta} = 2\lambda(\zeta - de)$$

$$\begin{aligned} \ddot{\rho} - \rho\dot{\varphi}(\dot{\varphi} + 2\cos\varphi) + 2\dot{\zeta}\sin\vartheta\cos\varphi + \zeta\sin\varphi\sin\vartheta\cos\vartheta - \\ - \rho(1 - \sin^2\varphi\sin^2\vartheta) + \frac{\partial\tilde{\Pi}}{\partial\rho} = \lambda\frac{\partial F}{\partial\rho} = \frac{2\rho\lambda}{1 - e^2} \end{aligned}$$

where  $\tilde{\Pi}$  is dimensionless gravitational potential of the asteroid

$\lambda$  is Lagrange's multiplier,

$\lambda < 0$  correspond to motions along internal surface of the ellipsoid,  
(the 'constrained' motion, the cable is tensed)

$\lambda = 0$  correspond to motions inside the ellipsoid (the 'free' motion or  
'the station has lost the constraint', the cable is weakened)

$\lambda > 0$  is impossible

# Lagrangian, Jacobi's integral

$$L = T_2 + T_1 + T_0 - \Pi(\rho, \zeta)$$

$$J = T_2 - T_0 + \Pi(\rho, \zeta) = \text{const}$$

## Integrable cases

1)  $\vartheta = 0$      There is a cyclic variable  $\varphi$

2)  $\vartheta = \pi/2$ ;      $y = 0$

## Equilibria types

$$\cos \varphi \sin \vartheta (\rho \sin \varphi \sin \vartheta + \zeta \cos \vartheta) = 0$$

**Coplanar equilibria**  $\varphi = \pm\pi/2$

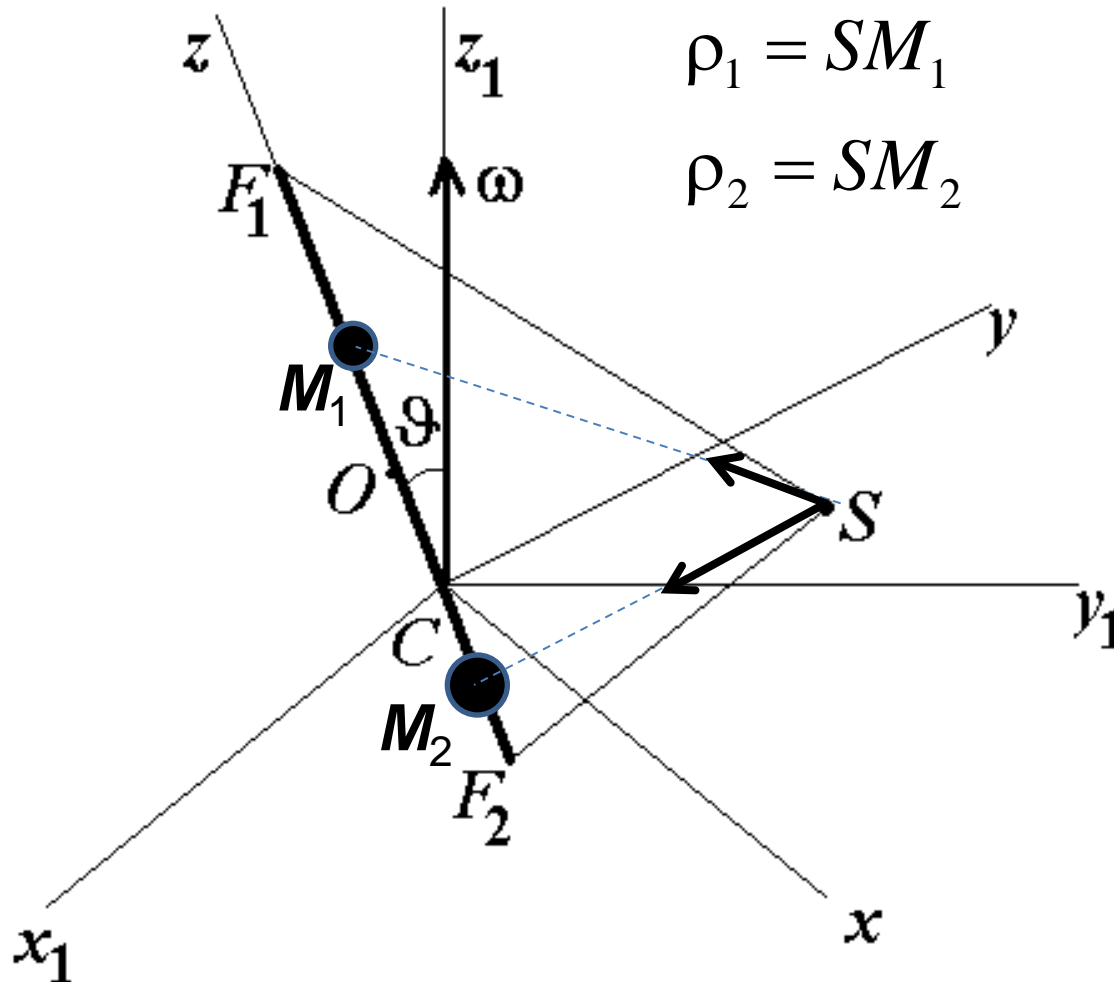
They belong to the plane  
composed by  $Cz$  and  $Cz_1$

**Triangular equilibria**  $\rho \sin \varphi + \zeta \cot \vartheta = 0$

They belong to the plane  $Cx_1y_1$

# The two-particles model

$$\tilde{\Pi} = -\alpha k^3 e^3 \left( \frac{\mu}{\rho_1} + \frac{1-\mu}{\rho_2} \right)$$



$$\rho_1 = SM_1$$

$$\rho_2 = SM_2$$

## Additional parameters

$$k = M_1 M_2 / OF_1$$

$$\mu = \frac{m_1}{m_1 + m_2}$$

$$\alpha = \frac{G(m_1 + m_2)}{\omega^2 |M_1 M_2|^3}$$

$$|d| < k < 2$$

$$0 < \mu \leq 1/2$$

$$\alpha > 0$$

## Integrable case $\mathfrak{g}=0$

The cyclic integral  $\rho^2(\dot{\varphi} + 1) = c$

Reduced motion equations

$$\ddot{\zeta} - 2\lambda(\zeta - de) + \frac{\partial \tilde{\Pi}}{\partial \zeta} = 0, \quad \ddot{\rho} - \frac{c^2}{\rho^3} - \frac{2\lambda\rho}{1-e^2} + \frac{\partial \tilde{\Pi}}{\partial \rho} = 0$$

New variable for motion on the ellipsoid surface

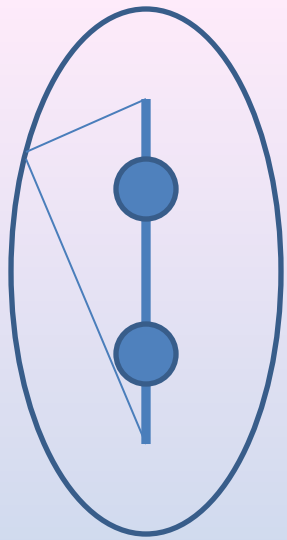
$$\rho = \sqrt{1-e^2} \sin \gamma, \quad \zeta = de + \cos \gamma, \quad 0 < \gamma < \pi$$

Jacobi's integral

$$\frac{1}{2}(1-e^2 \cos \gamma)\dot{\gamma}^2 + \tilde{\Pi} + \frac{c^2}{2(1-e^2) \sin^2 \gamma} = h = \text{const}$$

$$\lambda \leq 0 \quad \Leftrightarrow \quad \dot{\gamma}^2 - \frac{\sin \gamma}{\sqrt{1-e^2}} \frac{\partial \tilde{\Pi}}{\partial \rho} - \cos \gamma \frac{\partial \tilde{\Pi}}{\partial \zeta} + \left( \frac{c}{(1-e^2) \sin \gamma} \right)^2 \geq 0$$



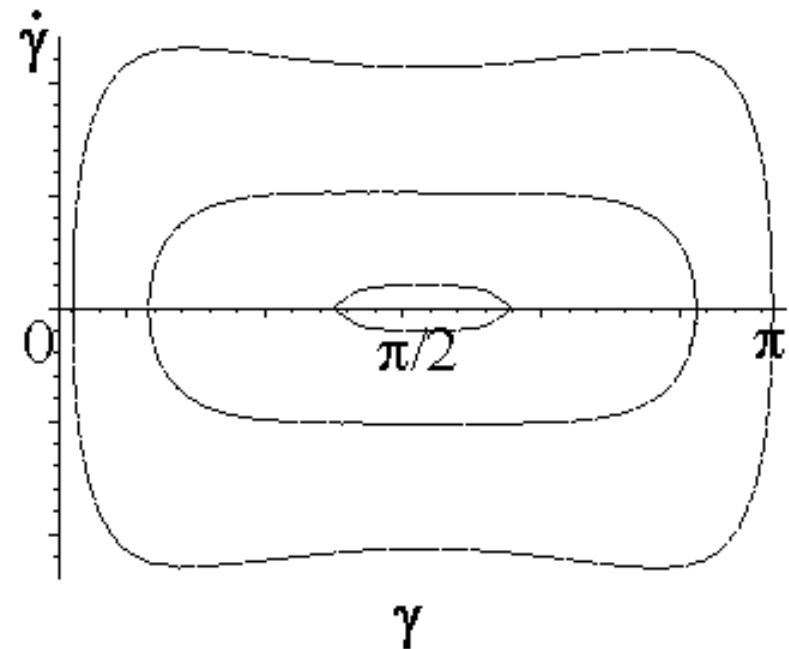
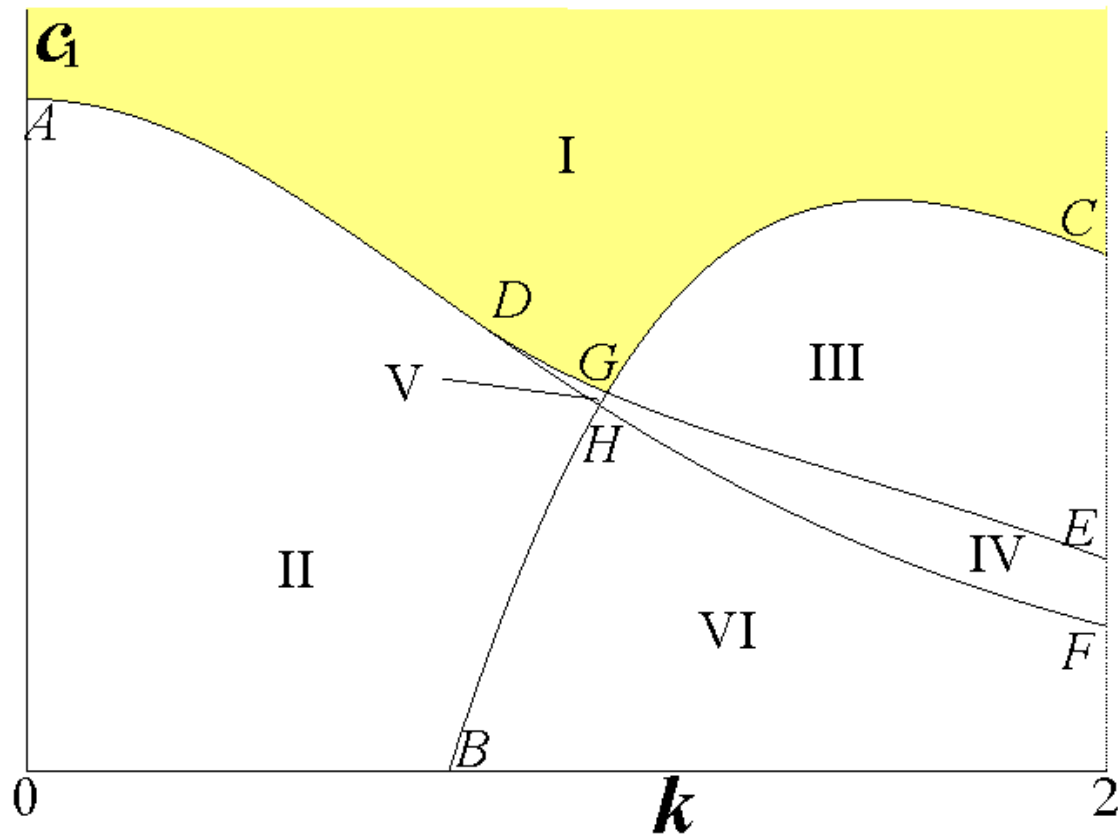


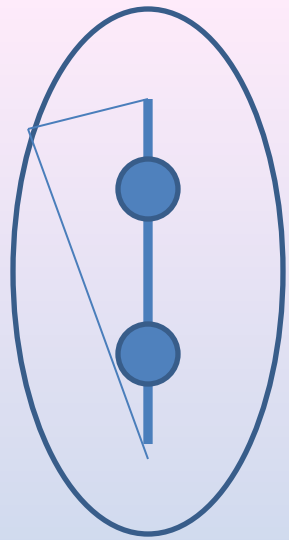
**Integrable case  $\mathfrak{I}=0$**

**The two-particles model**

**The full-symmetric case  $d=0, \mu=1/2$**

$$c_1 = c^2 / (\alpha k^3)$$



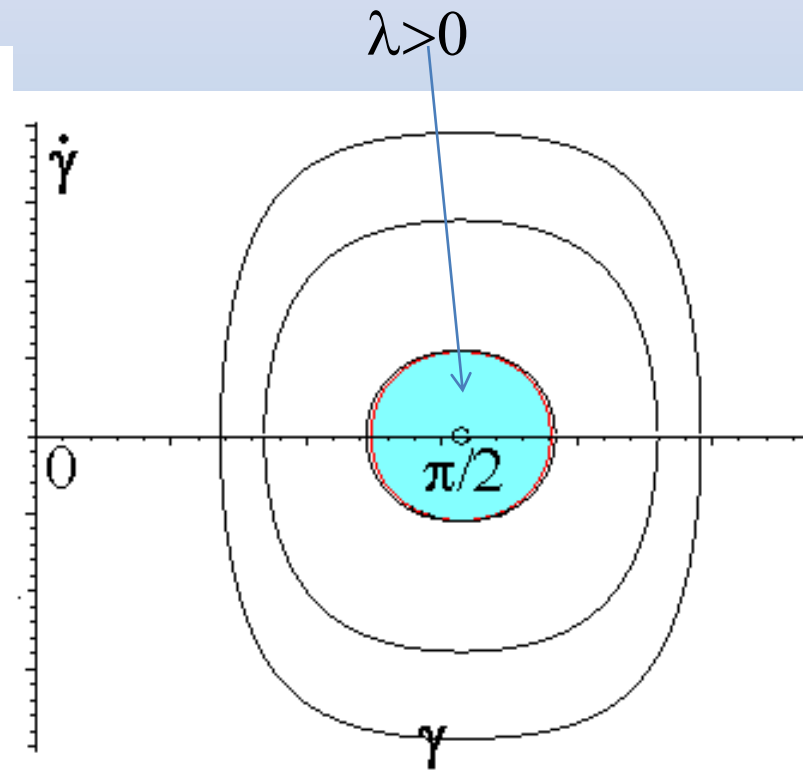
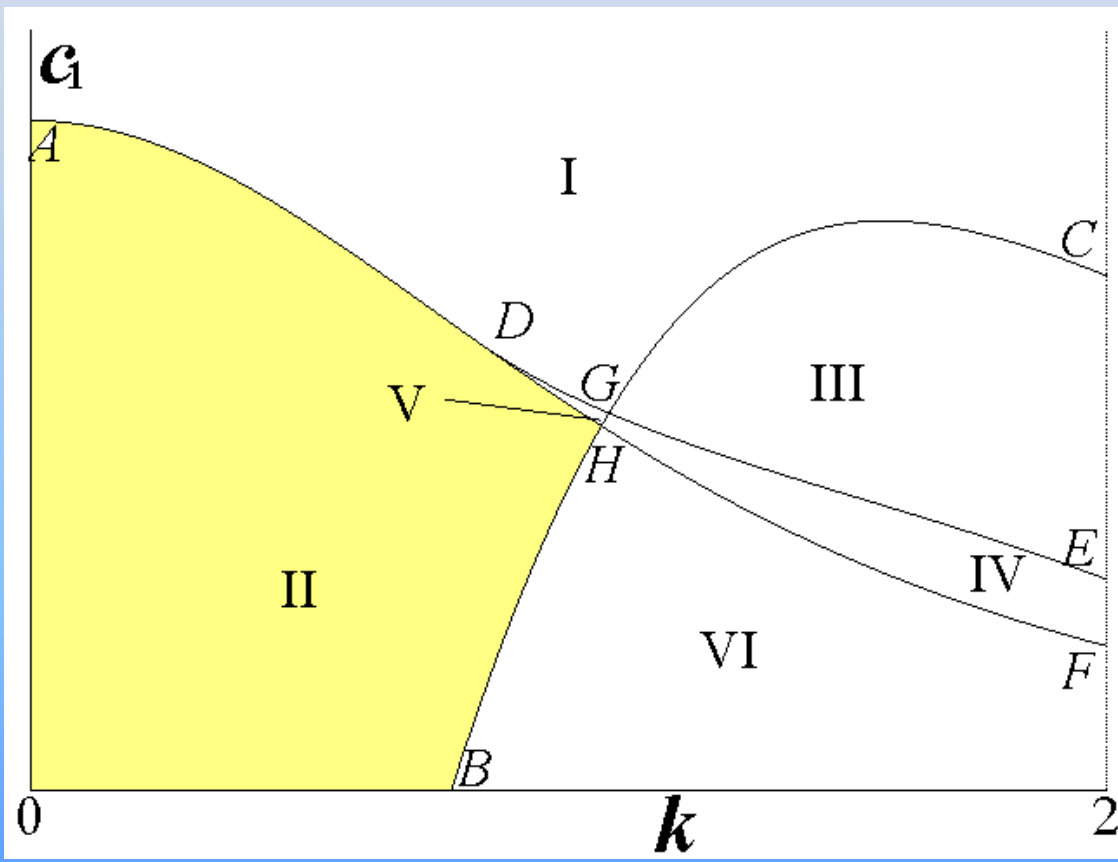


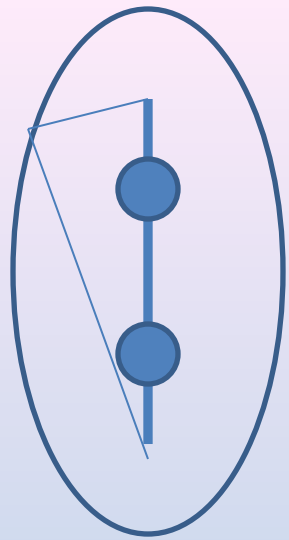
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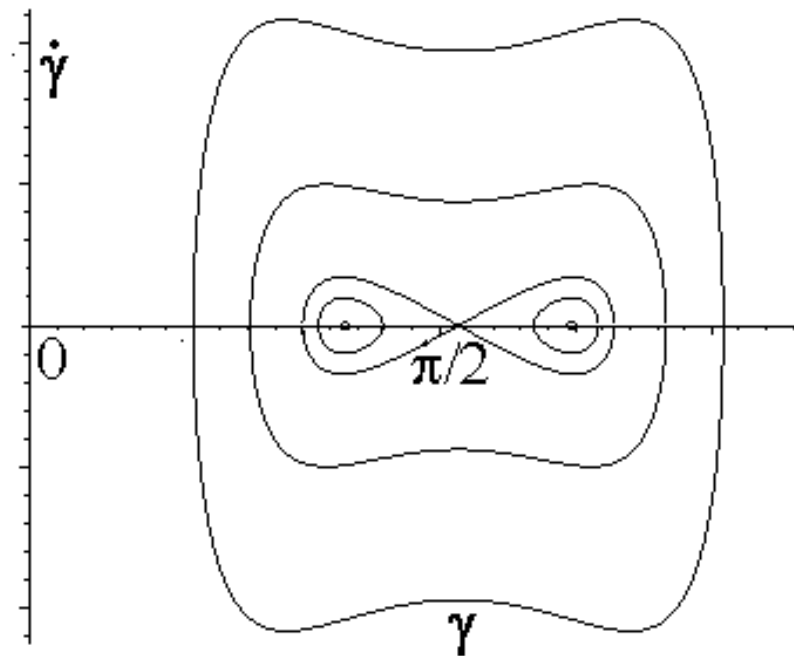
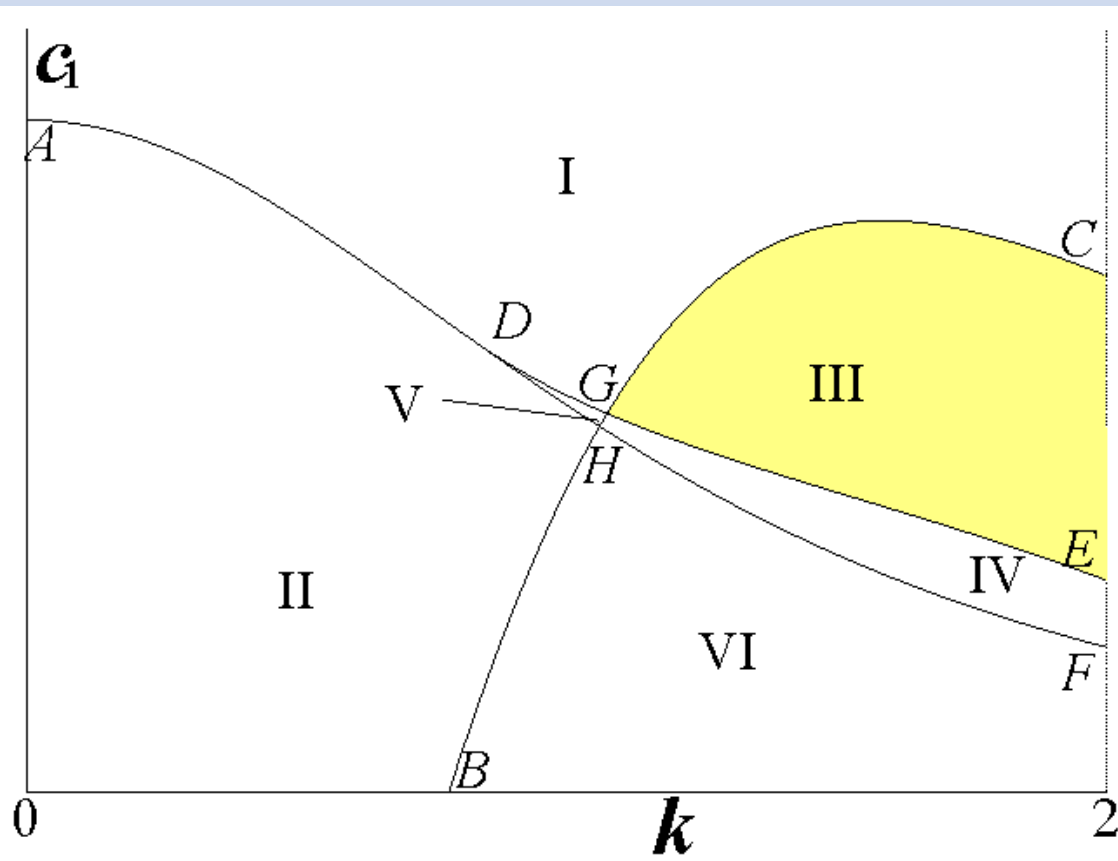


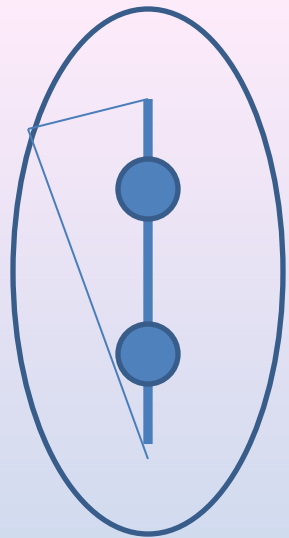
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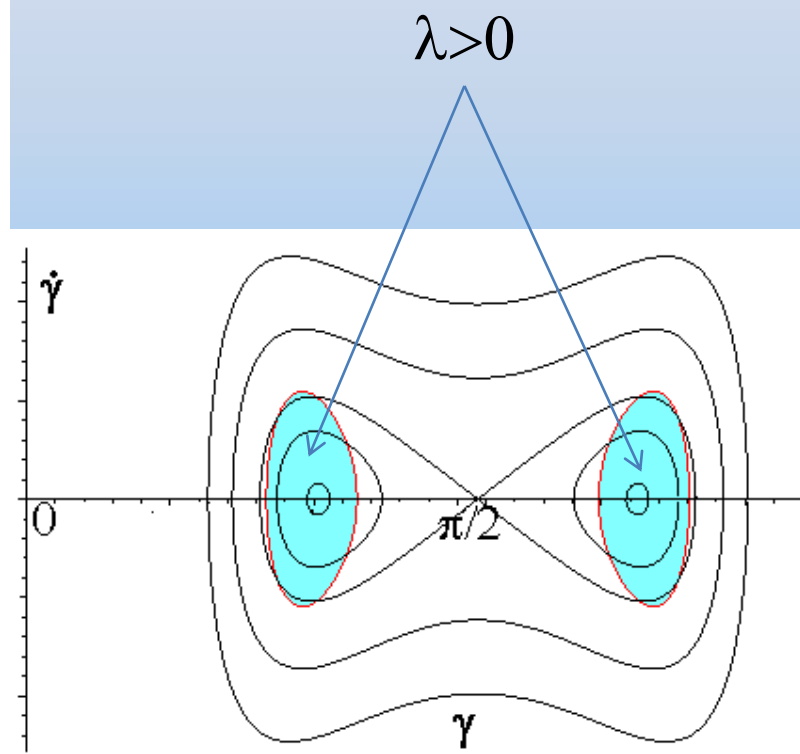
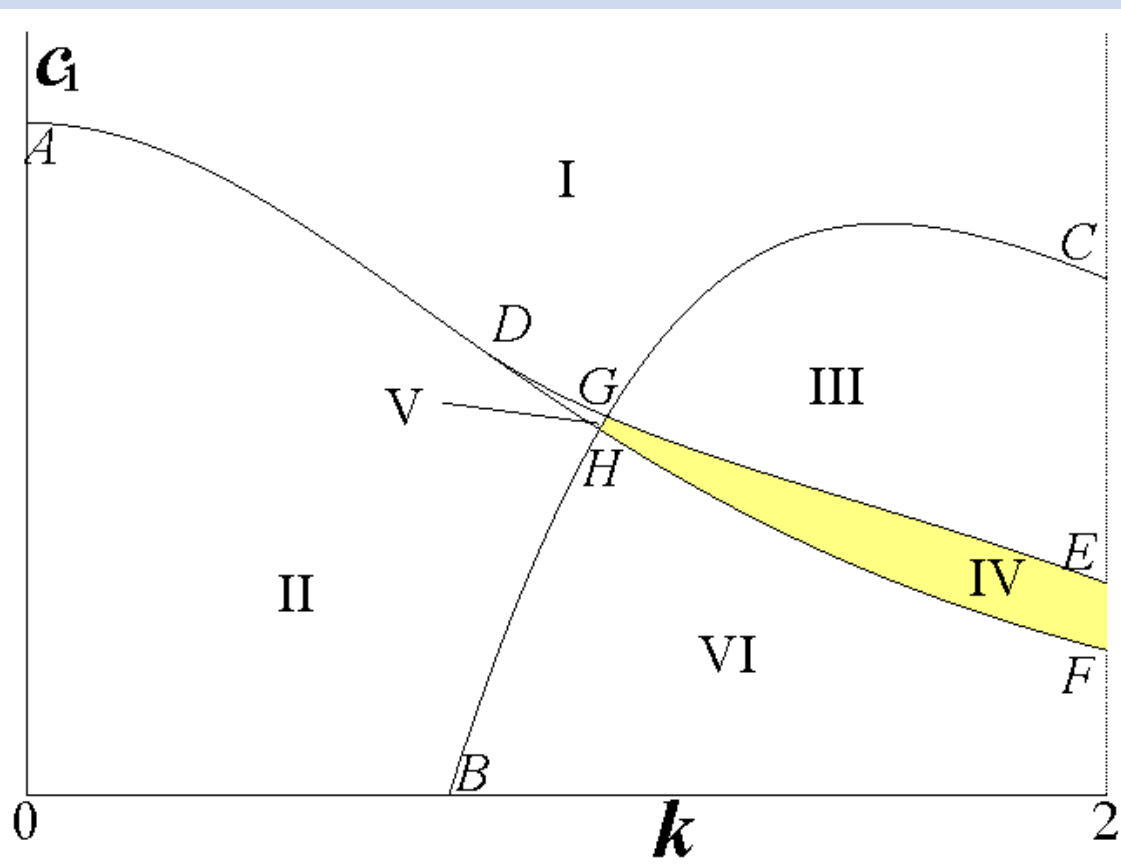


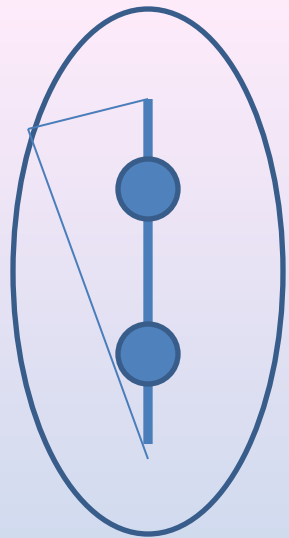
## Integrable case $\mathfrak{I}=0$

The two-particles model

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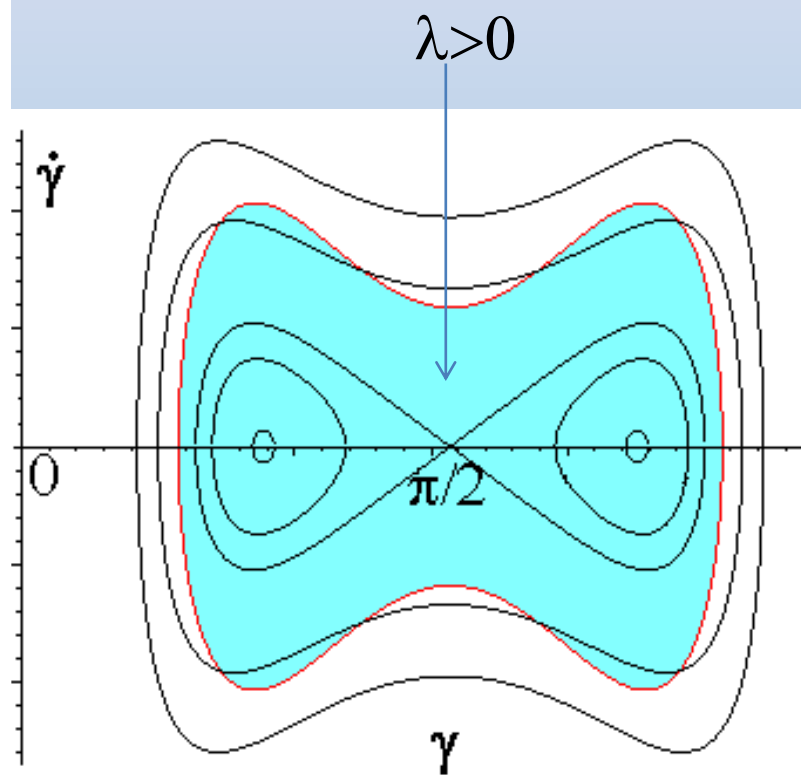
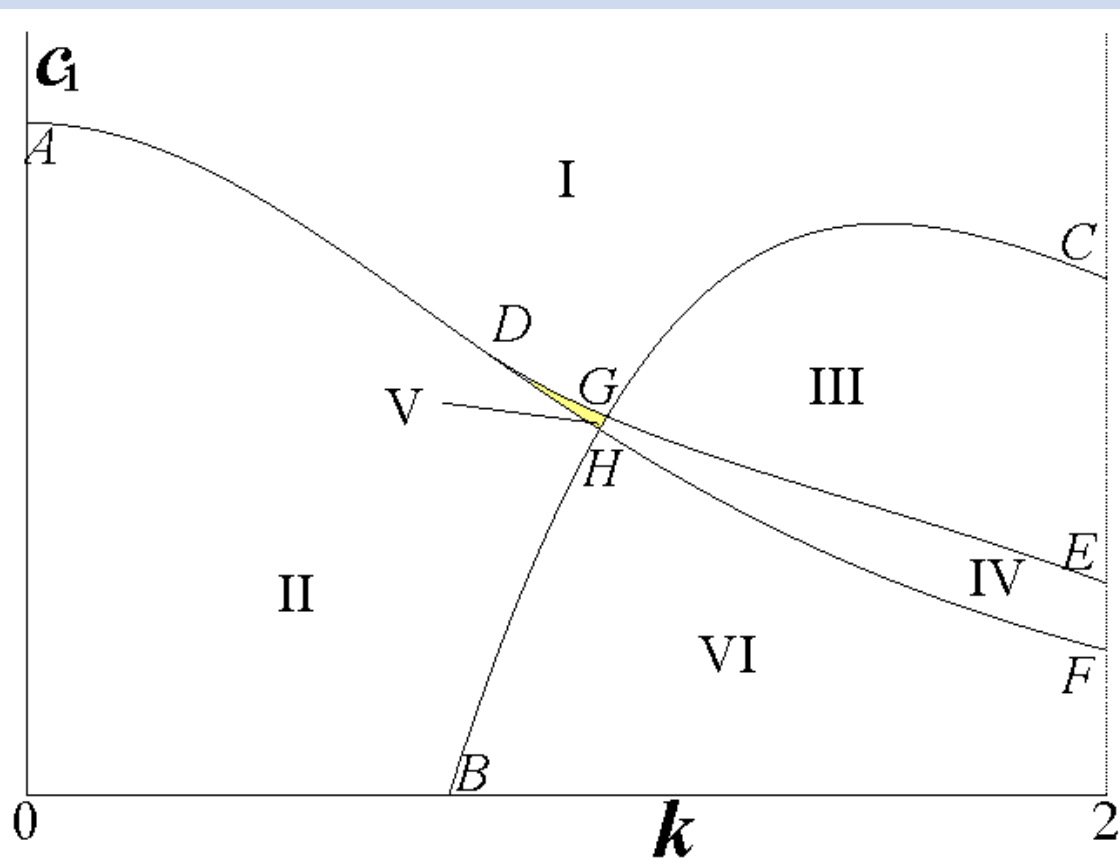


# Integrable case $\mathfrak{I}=0$

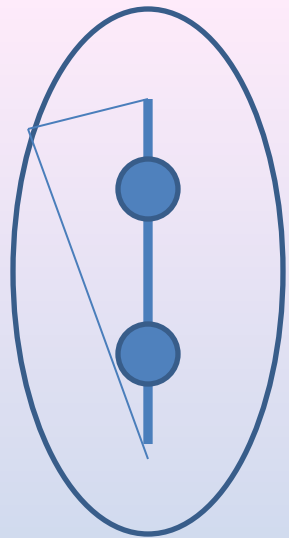
The two-particles model

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$$c_1 = c^2/(\alpha k^3)$$





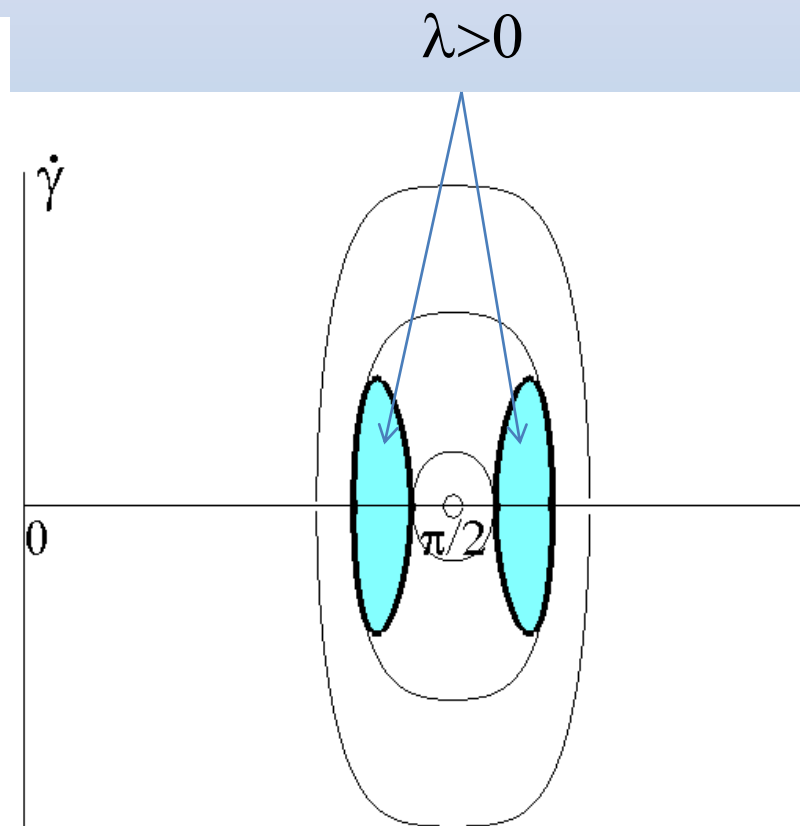
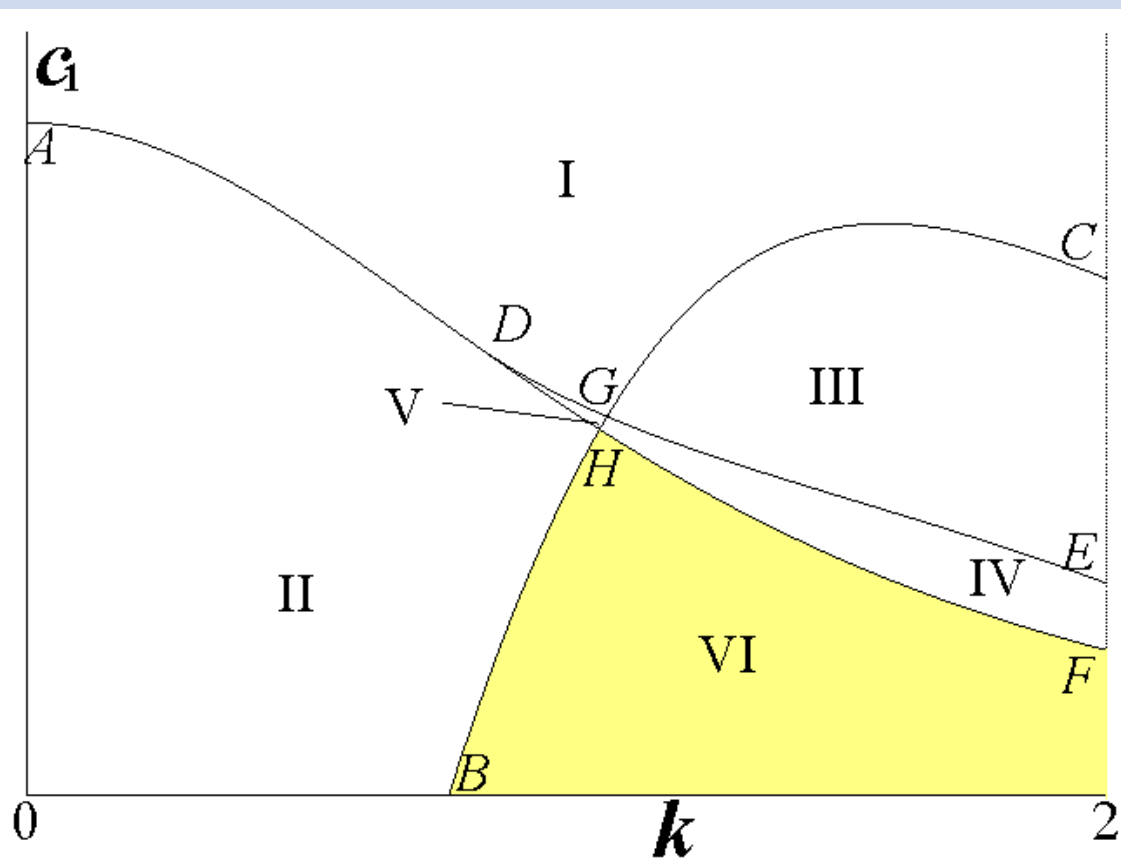


**Integrable case  $\mathfrak{I}=0$**

**The two-particles model**

**The full-symmetric case  $d=0, \mu=1/2$**

$$c_1 = c^2 / (\alpha k^3)$$



## Integrable case $\vartheta=\pi/2, y=0$

Motion equations

$$\ddot{\xi} + 2\dot{\zeta} - \xi + \frac{\partial \tilde{\Pi}}{\partial \xi} = \frac{2\lambda\xi}{1-e^2} \quad \ddot{\zeta} - 2\dot{\xi} - \zeta + \frac{\partial \tilde{\Pi}}{\partial \zeta} = 2\lambda(\zeta - ed)$$

New variable for motion along the ellipse

$$\rho = \sqrt{1-e^2} \sin \gamma, \quad \zeta = de + \cos \gamma, \quad 0 \leq \gamma < 2\pi$$

Jacobi's integral

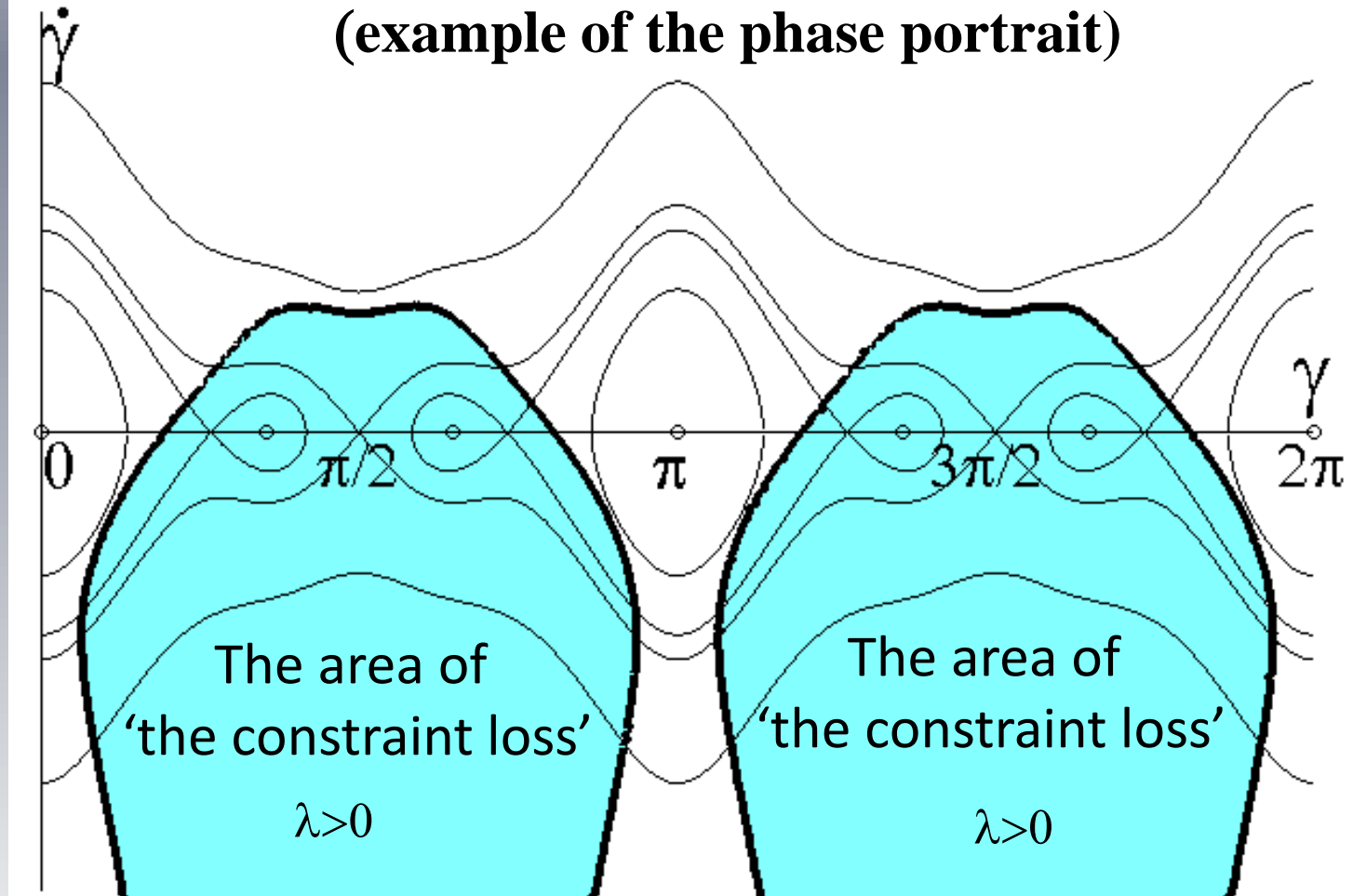
$$\frac{1}{2}(1-e^2 \cos^2 \gamma) \dot{\gamma}^2 + \tilde{\Pi} - de \cos \gamma - \frac{1}{2}e^2 \cos^2 \gamma = h = \text{const}$$

$$\lambda \leq 0 \Leftrightarrow$$

$$\dot{\gamma}^2 + \frac{2(1-e^2 \cos^2 \gamma)}{\sqrt{1-e^2}} \dot{\gamma} + de \cos \gamma + 1 - \frac{\sin \gamma}{\sqrt{1-e^2}} \frac{\partial \tilde{\Pi}}{\partial \xi} - \cos \gamma \frac{\partial \tilde{\Pi}}{\partial \zeta} \geq 0$$

## Integrable case $\vartheta=\pi/2$ , $y=0$

The full-symmetric case  $d=0$ ,  $\mu=1/2$   
(example of the phase portrait)



The system phase portrait is complex but only equilibria in the ellipse vertexes really exist

## Triangular equilibria

$$\frac{\partial \tilde{\Pi}}{\partial \zeta} + 2\lambda d - (1 + 2\lambda)\zeta = 0$$

$$\frac{\partial \tilde{\Pi}}{\partial \rho} - \left(1 + \frac{2\lambda}{1 - e^2}\right)\rho = 0$$

The cable doesn't weaken if

$$\lambda \leq 0 \quad \Leftrightarrow \quad \frac{2\zeta - ke(1 + 2\mu)}{e\zeta + d(1 - e^2)} \leq 0$$

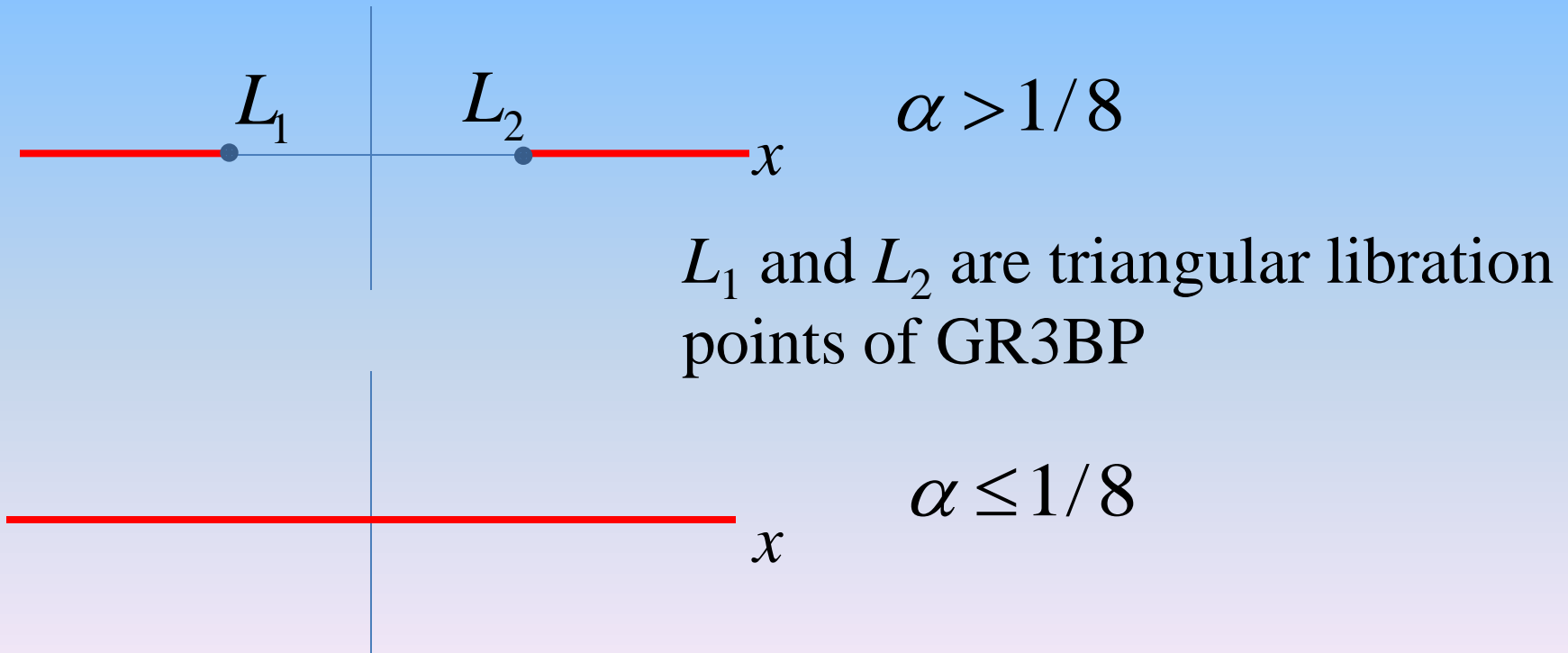
Let the two-particle model be applicable to the asteroid. In this case using A.P.Ivanov theorem it can be shown that all triangular equilibria, excepting triangular libration points of V.V.Beletsky GRC3BP, are **stable** if *motions along the cable are forbidden*

Fixing an asteroid, i.e. fixing values of  $k, \mu, \alpha, \vartheta, d$  we construct sets of triangular equilibria for the varied cable length. Following situations are possible

# Triangular equilibria for the two-particles model

The 'full-symmetric case'  $\mu = 1/2$ ,  $d = 0$

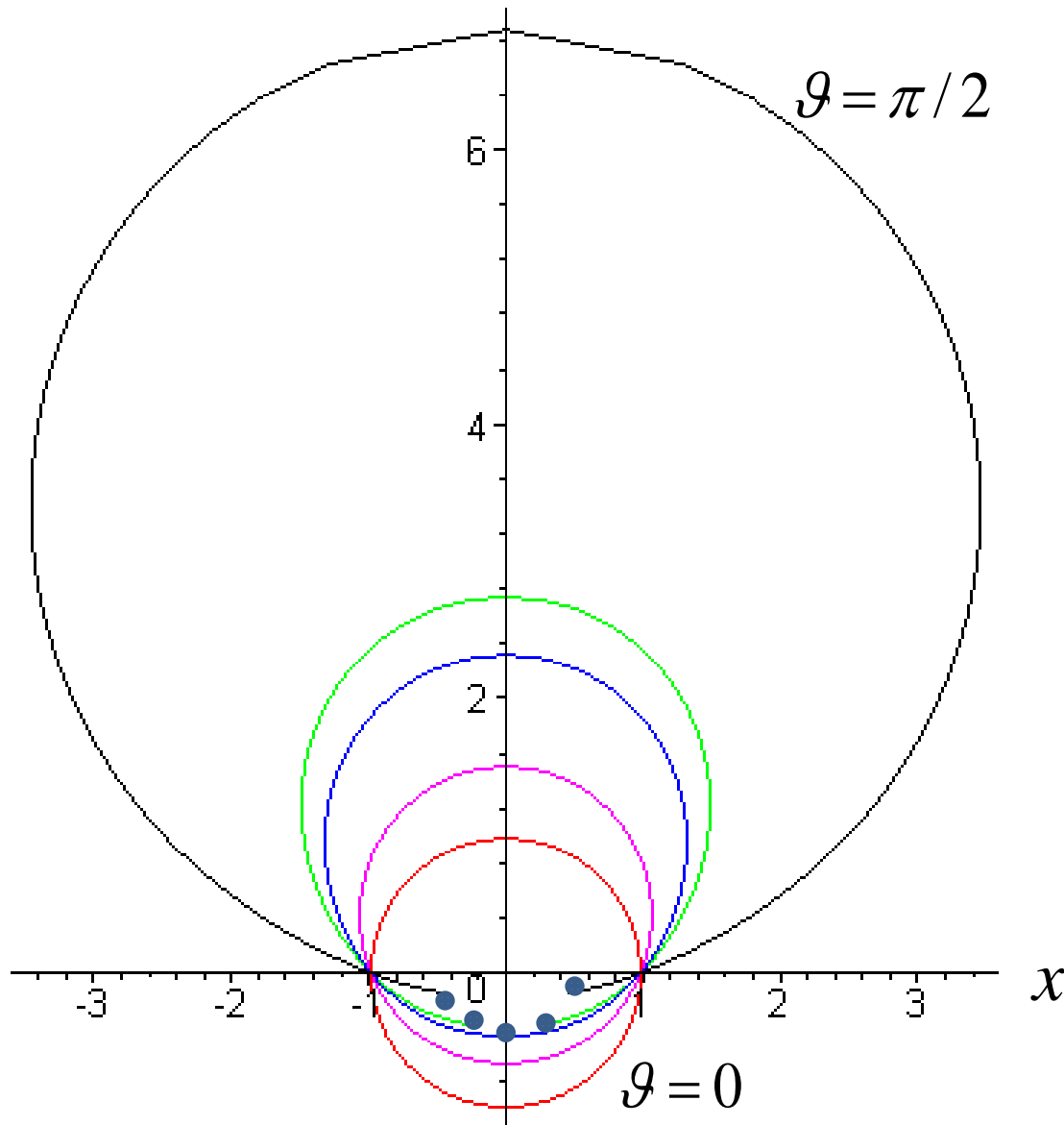
**2 equilibria**  $z = 0$ ;  $\rho = \sqrt{1 - e^2}$ ;  $\varphi = 0, \pi$ ;  $r_1 = r_2 \geq \alpha^{1/3} ek$   
are ***unstable*** for any values of parameters





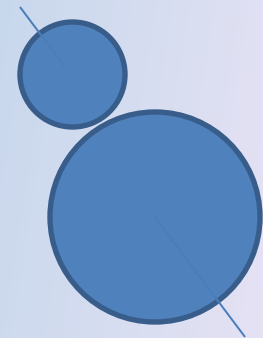
# Triangular equilibria for the two-particles model

**Common cases**  $\mu < 1/2$ ,  $d > 0$   $\alpha > 1/8$



**2 or 4 equilibria for any admissible  $e$**

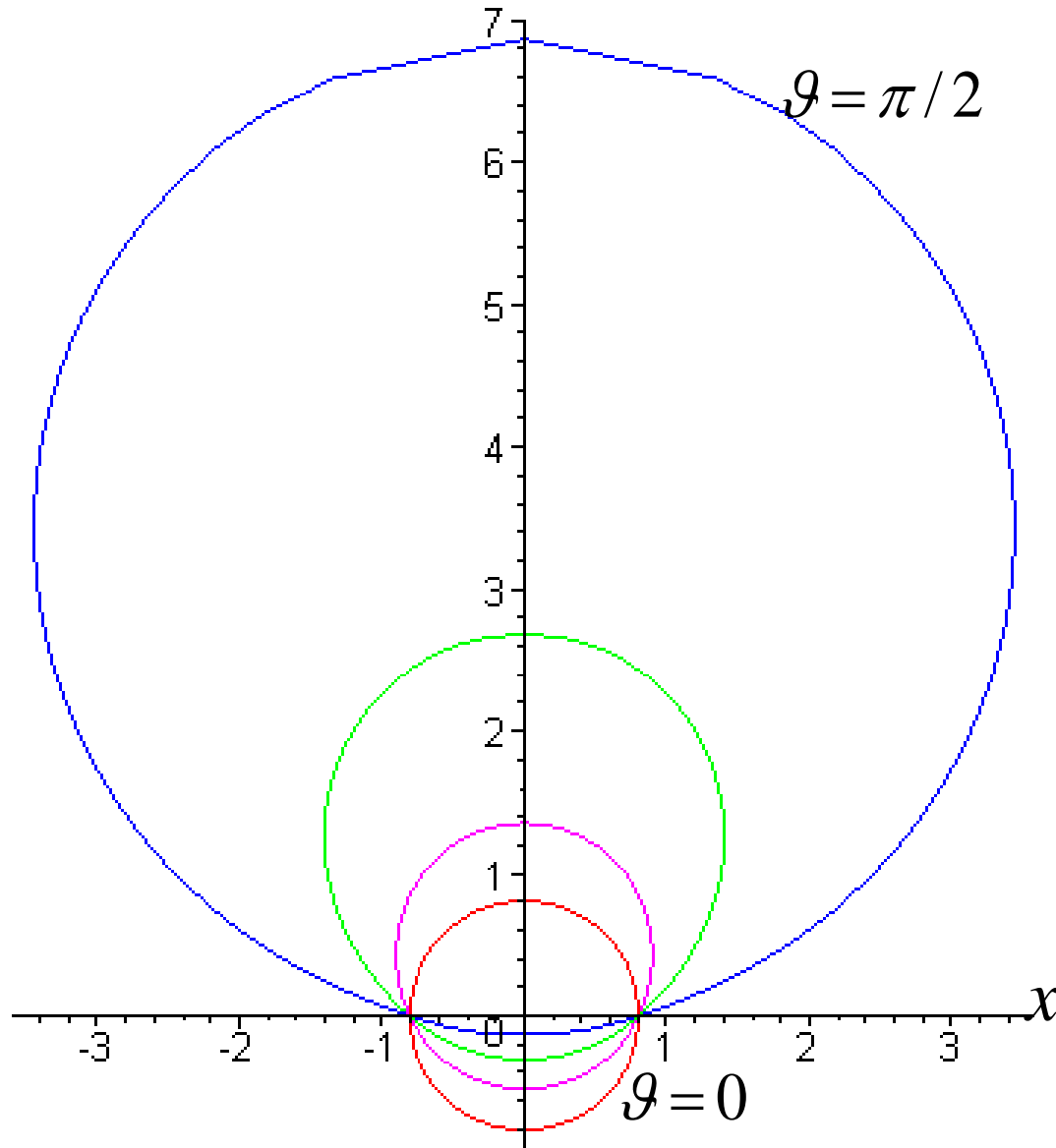
Each color corresponds to a fixed value of  $\mathcal{E}$



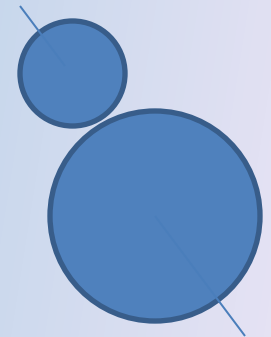
Fat blue points are the triangular libration points of Beletsky's problem

# Triangular equilibria for the two-particles model

**Common cases**  $\mu < 1/2$ ,  $d > 0$   $\alpha < 1/8$



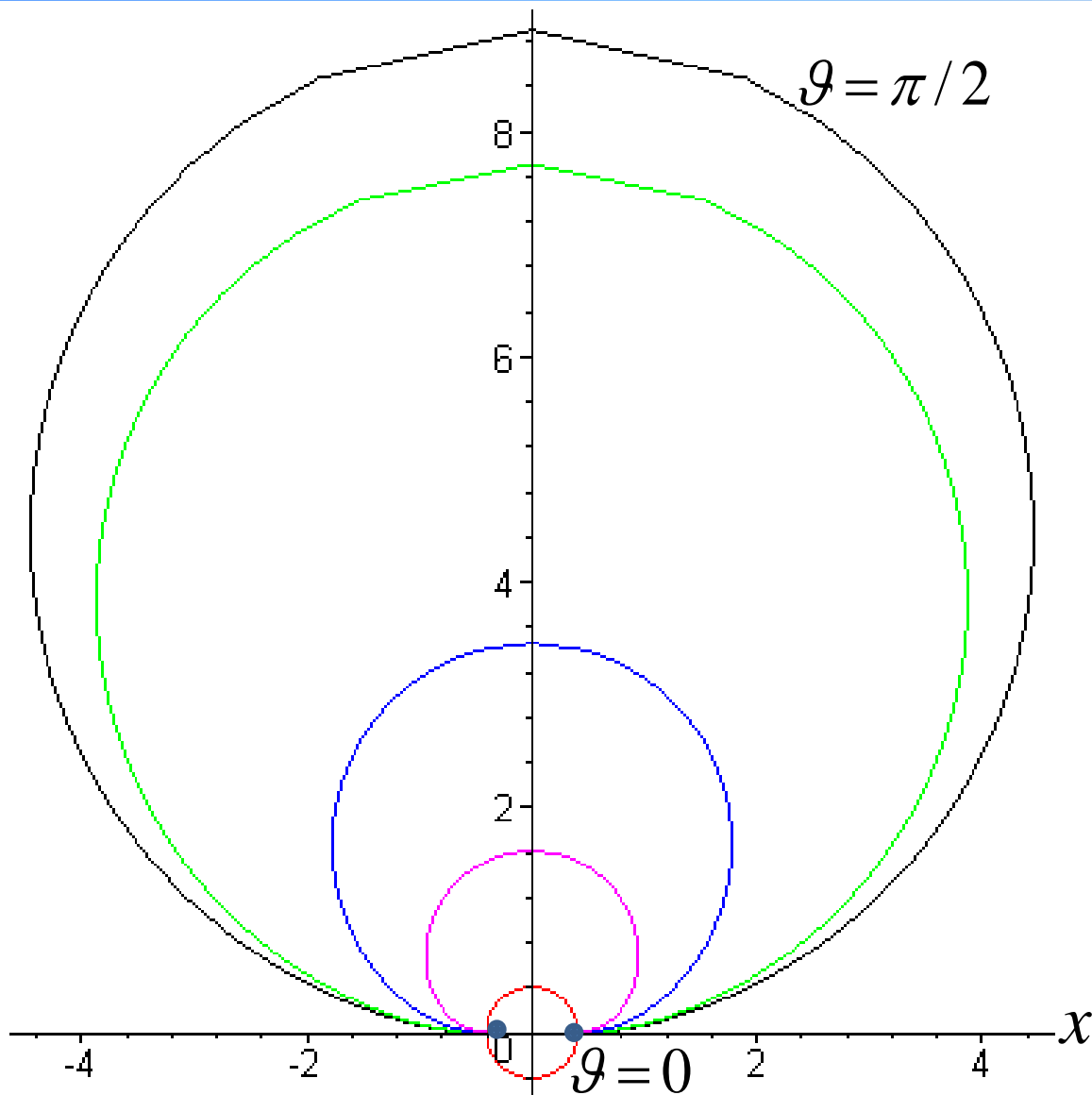
**4 equilibria for any  
admissible  $e$**



Each color corresponds to a  
fixed value of  $\vartheta$

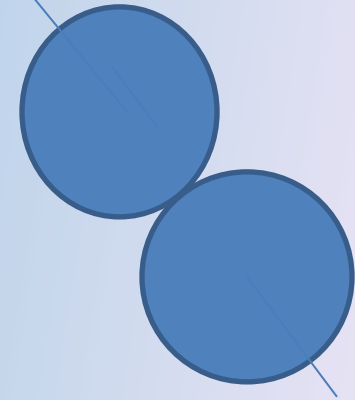
# Triangular equilibria for the two-particles model

The symmetric dumbbell case  $\mu=1/2$ ,  $d>0$   $\alpha>1/8$



**2 equilibria for any admissible  $e$**

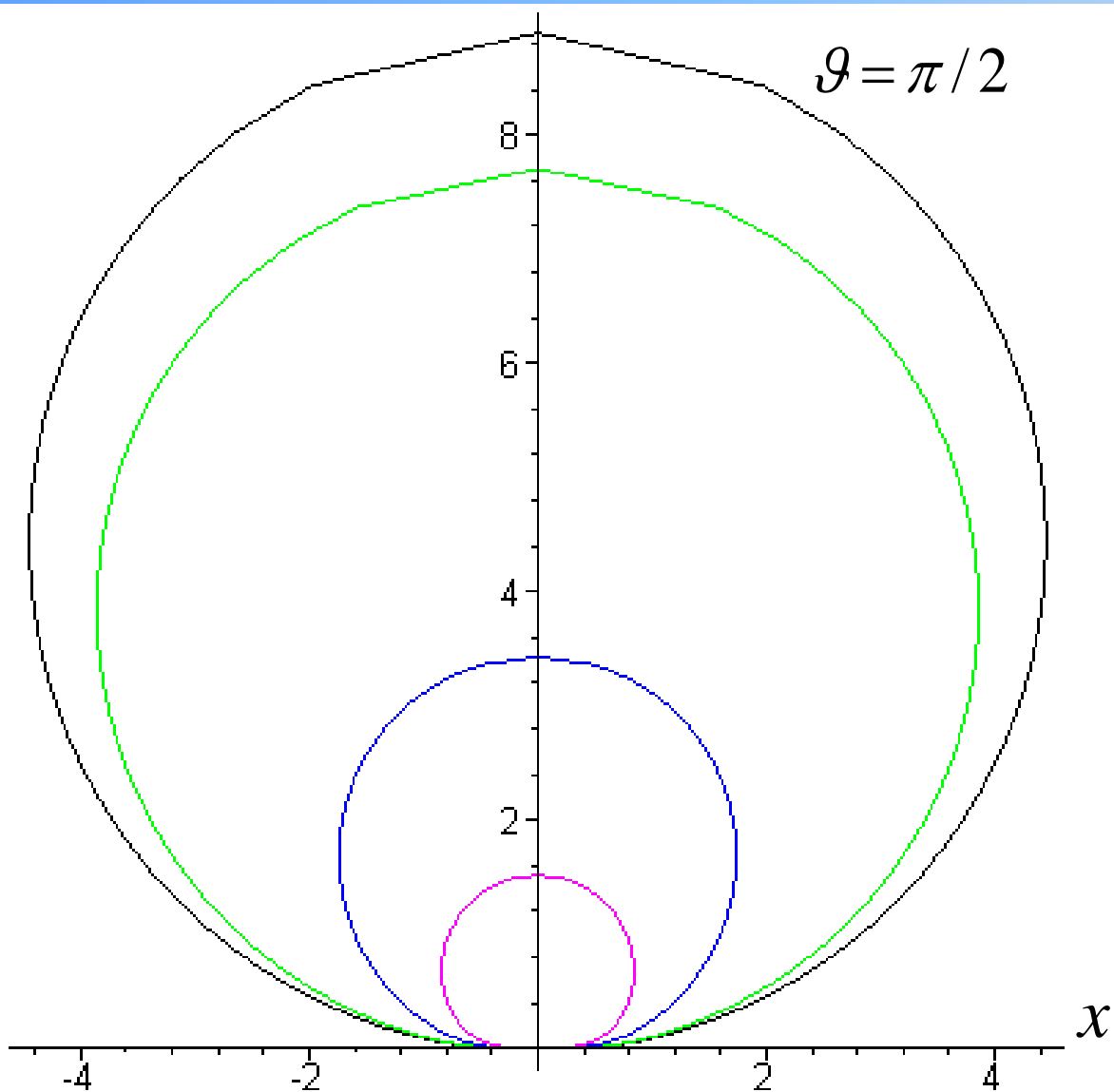
Each color corresponds to a fixed value of  $\vartheta$



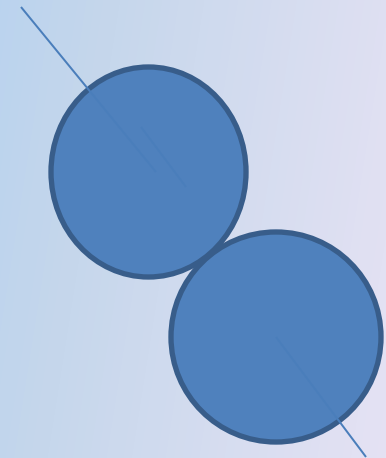
**Red** is the ring of triangular libration points

# Triangular equilibria for the two-particles model

The symmetric dumbbell case  $\mu=1/2$ ,  $d>0$   $\alpha<1/8$



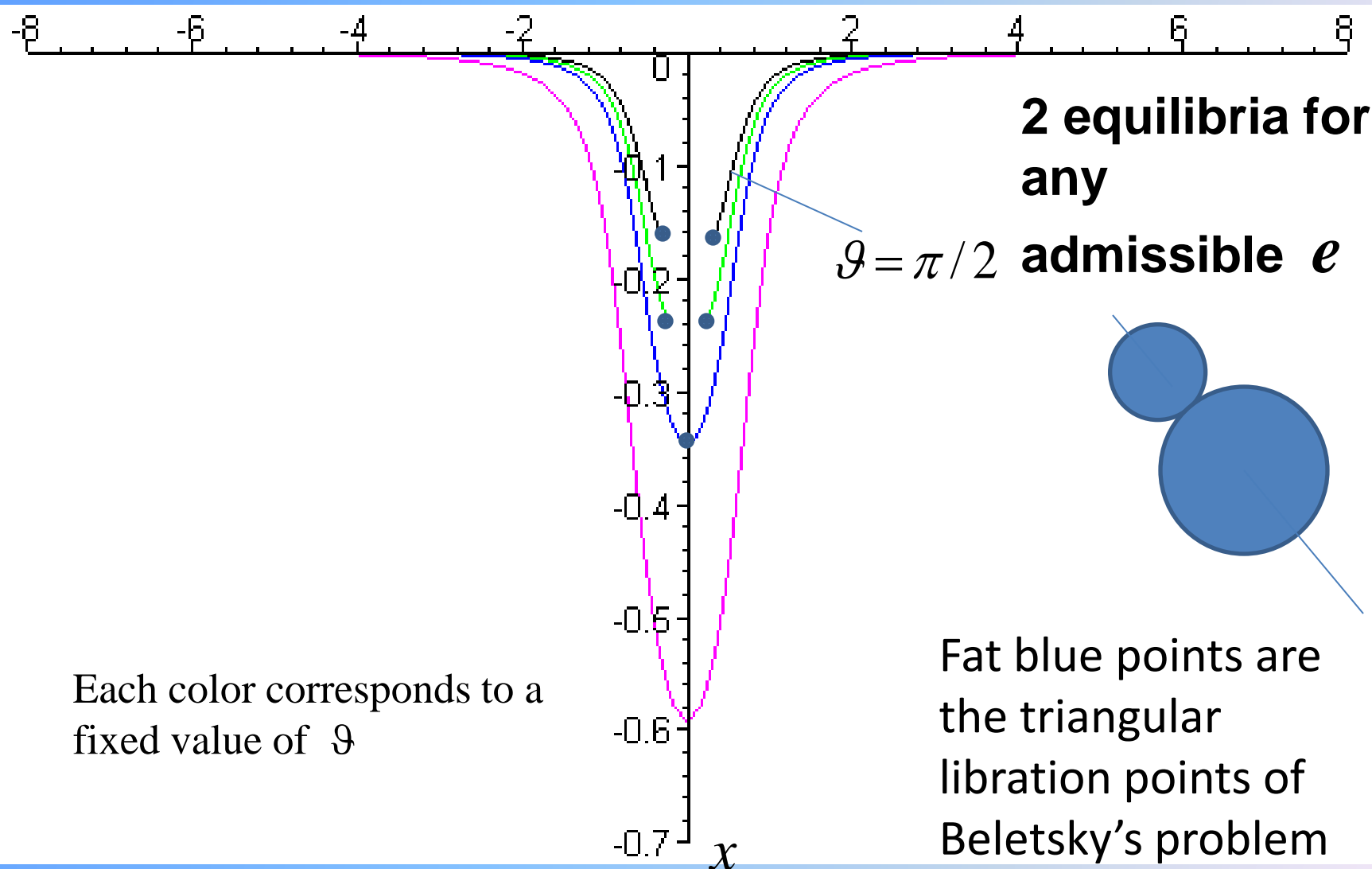
**2 equilibria for  
any admissible  $e$**



Each color corresponds to a  
fixed value of  $\vartheta$

# Triangular equilibria for the two-particles model

The symmetric elevator case  $\mu < 1/2$ ,  $d = 0$   $\alpha > 1/8$



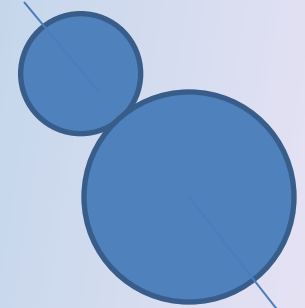
# Triangular equilibria for the two-particles model

**‘The big tower’ case**

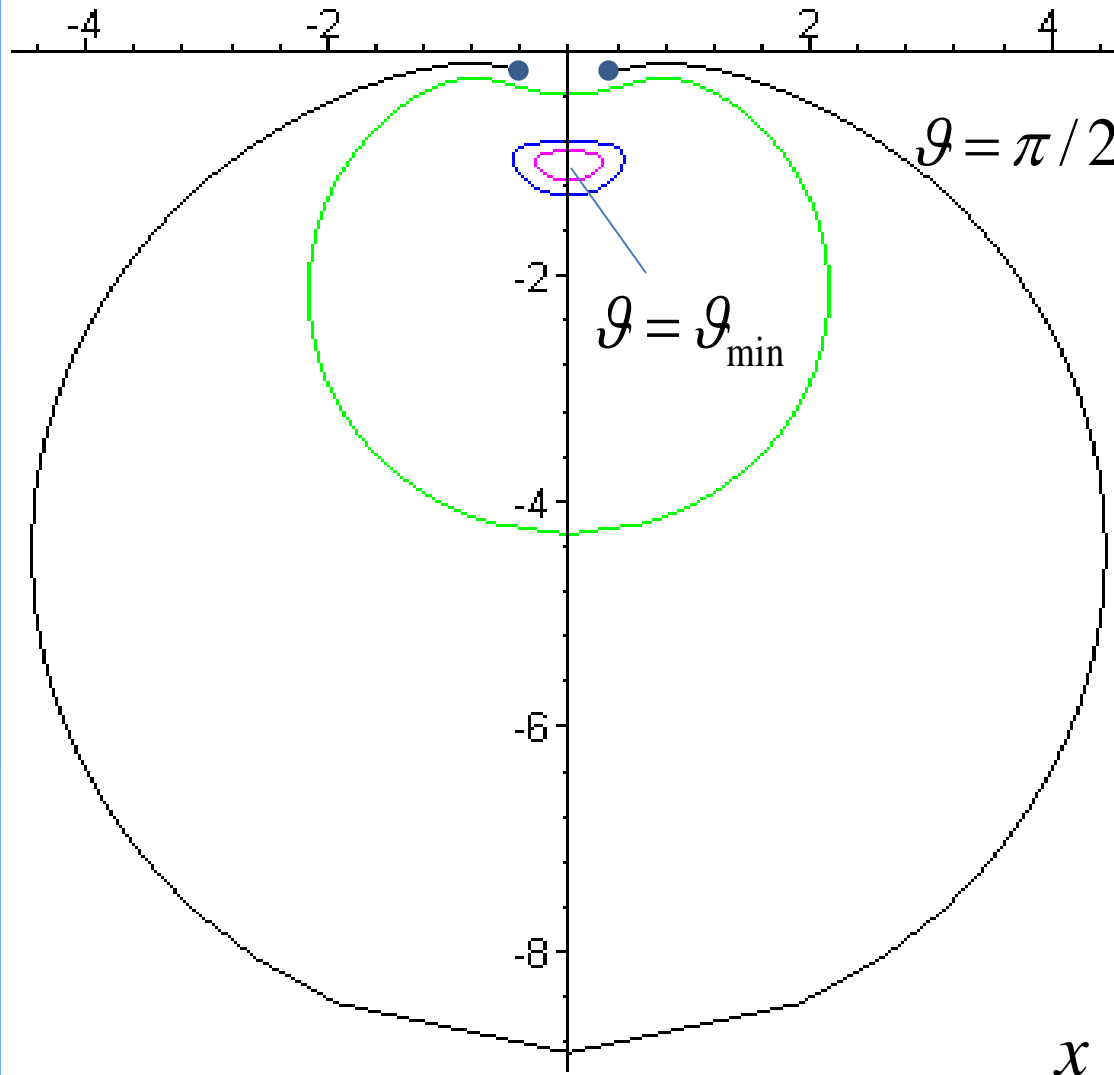
$$\mu < 1/2, \quad d < 0 \quad \alpha > 1/8$$

**2 equilibria for  
any admissible  $e$**

Each color corresponds to a  
fixed value of  $\mathcal{J}$



Fat blue points are  
the triangular  
libration points of  
Beletsky's problem



## Instead of **conclusions** there are new **problems**

- 1) Studying of integrability and searching for non-trivial integrable cases
- 2) Complete studying of equilibria stability
- 3) Studying of perturbed system
- 4) Previous problems for other models of gravitation
- 5) Formulation of the problem for three-axial asteroids
- 6) Previous problems for the formulated problem
- 7).... $\infty$ ) etc. etc.

I am often asked when I think the first space elevator might be built. My answer has always been: about 50 years after everyone has stopped laughing. Maybe I should now revise it to 25 years. (*Arthur C. Clarke*)

The classical space elevator length with the opposite mass is more than 36000 km

The asteroid elevator length is about tens or hundreds km

**What of these projects to realize easier?**

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Discussions with prof. S.Ya.Stepanov was the reason to formulate this problem.

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**Merci beaucoup pour votre attention**

**Thank you for your attention**