Light time calculation in high precision space navigation

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The standard Moyer's mode

Our model

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Conclusions

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Plan

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Space Navigation is based on a radio exchange of information between the probe, equipped with an antenna and a transponder, and one or more ground stations, equipped with a clock.





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Ephemeris of a space mission is built following this procedure :



The ephemeris is necessary for :

- operational goals space probe navigation
- scientific goals measurements in fundamental physics

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Observables : Ranging

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Ranging is basically the 2-way light-time + calibrations :



• Transponder delay ($\approx 2.5 \ \mu s$)

where $R_{ab} = |\boldsymbol{x}_b - \boldsymbol{x}_a|$ and c is the speed of light.

Observables : Doppler



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Differential Doppler :



Doppler shift is linked to the radial velocity of the observed body :

$$\frac{\Delta\nu'}{\nu_{1'}} = \frac{T_{3'} - T_{1'}}{T_{1'}} = M_2 f_T \dot{\rho}'$$

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In $\dot{\rho}'$ constant (or slowly changing) terms $(\delta \rho', \delta t_{2'})$ simplify.

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- Separation of reception and re-emission events $t_3 = t_2 + \delta t$
- Modification of the 2-way light-time and of the Ranging/Doppler observables

The Ranging observable in the 2 models

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At the Newtonian approximation :

$$\begin{split} \text{Moyer} : \rho' &= \frac{R_{1'2'}}{c} + \frac{R_{2'3'}}{c} + \delta C + \delta t \\ \text{Alternative} : \rho &= \frac{R_{12}}{c} + \frac{R_{34}}{c} + \delta C + \delta t \end{split}$$

supposing that the reception time $t_4 = t_3^\prime$ is the same for the two models :

$$egin{array}{rcl} m{x}_3' &=& m{x}_4 & m{x}_2' = m{x}_3 \ m{x}_3 &=& m{x}_{2+\delta t} & m{x}_1' = m{x}_{1+\Delta
ho} \end{array}
ightarrow
ightarrow$$

we obtain :

$$\Delta \rho = \rho - \rho' = \delta t \frac{(\boldsymbol{v}_1^{GS} - \boldsymbol{v}_2^{SC}) \cdot \boldsymbol{N}_{12}}{c} + \mathcal{O}(c^{-2})$$

Modifications in the Doppler observable

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The Doppler signal is computed by :

$$\frac{\Delta\nu}{\nu_1} = M_2 f_T \dot{\rho}$$

- In Moyer's model, the Doppler observable is independent from the transponder delay.
- In the alternative model, the transponder delay contribution on the Ranging depends on the spacecraft and ground station state : Δρ is not constant.

Since $\Delta \rho$ is not constant, $\Delta \dot{\rho} \neq 0$: the explicit computation of δt modifies the Doppler observable.

Application to a real case

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Earth flyby trajectory by Near and Rosetta

- Ephemeris provided by the NASA Naif/Spice toolkit
- This configuration is favorable for $\Delta \rho$ and $\Delta \dot{\rho}$



Ranging difference between the two models

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Computation of

$$\Delta \rho = \rho - \rho' = \delta t \frac{(\boldsymbol{v}_1^{GS} - \boldsymbol{v}_2^{SC}) \cdot N_{12}}{c} + \mathcal{O}(c^{-2})$$

with real spacecraft ephemeris :



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with real spacecraft ephemeris :





High dependency of the introduced terms

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High dependency of the Ranging and Doppler difference between the two models, following the spacecraft-ground station configuration.



Fig a : Ranging observation of different probes trajectories

Fig b : Doppler observation of different probes trajectories

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Impact of $\Delta\rho$ on the orbit reconstruction



Fig : Pre-post fit residuals

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The effects of the transponder delay are almost, even if not completely, absorbed by the fit.

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- the transponder delay influence on the light-time calculation is subtler than the addition of a constant term;
- a rigorous treatment of the transponder delay in the light-time computation does have an influence on the Doppler calculation;
- the error is of the order of several cm for actual transponders $(\approx 2.5 \mu s)$: the standard approximation is acceptable for most operational goals at present.

• what about future and past observations?